# MATH-305 Numerical Methods

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# 3. Bisection Mthd

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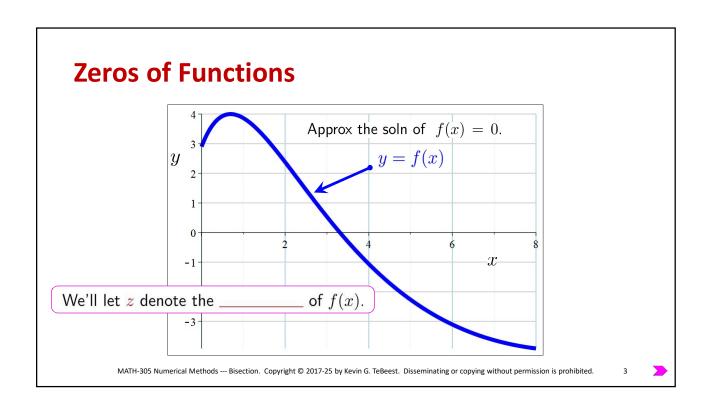
## Ch. 1 Zeros of Functions

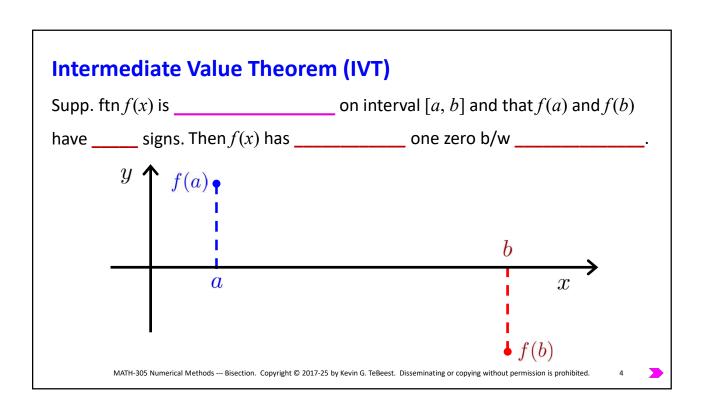
Here we seek a soln of a single \_\_\_\_\_\_ eqn involving one unknown.

**Example 1:** Solve the eqn for x:  $e^{-x} = \cos x$ .

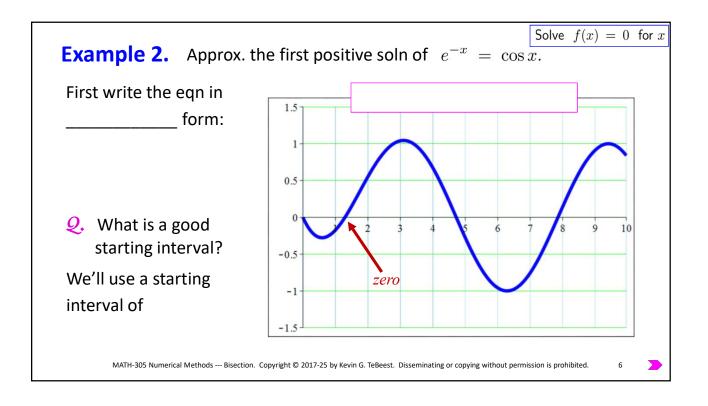
Zero Form	Root Form	
$e^{-x} - \cos x = 0$	$e^{-x} = \cos x$	
f(x) = 0	Any eqn in zero form.	
A soln is called a of $f$ .	A soln is called a of eqn.	
A zero of $f$ is an of the of $f$ .	Most of the mthds require the eqn in form.	

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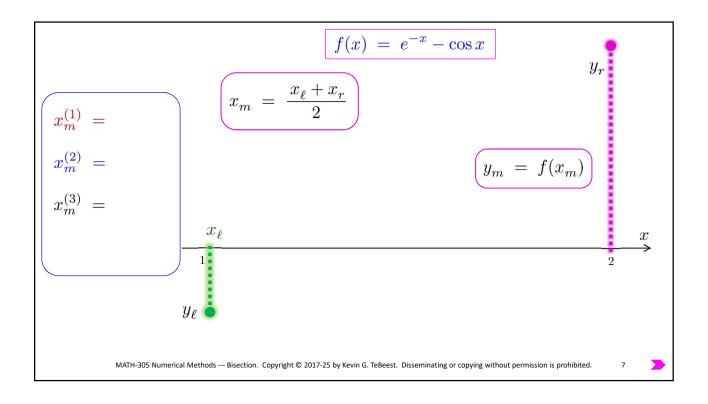




Bisection Method   Interval Halving			
To approx. a zero of $ftn f(x)$ , select a starting interval $[a,b]$ satisfying the			
We reserve $a$ and $b$ for the	of the		
interval.			
For computational convenience, we denote $a$ by $x_\ell$ and $b$ by $x_r$ , and let			
Ensure that $y_\ell$ and $y_r$ have signs.*			
* So the points $(x_\ell,y_\ell)$ and $(x_r,y_r)$ are on the of ftn $f(x)$ and are on opposite sides of	of the axis.		
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Solve f(x) = 0 for x



1. Each $x_m$ , called an $\_\_\_\_$ , a	approxs the zero $z$ of $ftn f$ .
2. The process of repeating steps to obtain each	ch iterate is called an
3. Performing iterations is called	
With enough iterations, the iterates converge to $z$ :	·
with chough iterations, the iterates converge to 2.	·
When convenient, we'll let $x_m^{(n)}$ denote the in	terate.

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**General Definitions** 

E.g.,  $x_m^{(4)}$  is the \_\_\_\_\_ iterate.

**Do Ex 2.** 
$$f(x) = e^{-x} - \cos x$$
,  $x_m = \frac{x_\ell + x_r}{2}$  Use radians!

Iter n=1:

$$\begin{array}{lll} x_\ell \,=\, 1.0 \,, & y_\ell \,=\, f(x_\ell) \,=\, f(1) \,=\, -0.1724 \ldots, \\ x_r \,=\, 2.0 \,, & y_r \,=\, f(x_r) \,=\, f(2) \,=\, +0.5514 \ldots, \end{array} \qquad \begin{array}{ll} \text{From the} \\ \text{previous slide}. \end{array}$$

$$x_m = \frac{x_\ell + x_r}{2} =$$
,  $y_m = f(x_m) = +0.1523...$ 

Sign Test:  $y_{\ell}$   $y_{m}$   $y_{r}$ 

So the zero of f is b/w

I.e., the zero of f is on interval

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$$x_m = \frac{x_\ell + x_r}{2}$$
  $f(x) = e^{-x} - \cos x$  Use radians!

Iter n=2:

Sign Test:  $y_{\ell}$   $y_{m}$   $y_{r}$ 

So the zero of f is b/w

I.e., the zero of f is on interval

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$$x_m = \frac{x_\ell + x_r}{2}$$
  $f(x) = e^{-x} - \cos x$  Use radians!

Iter n = 3:

So the zero of f is b/w

I.e., the zero of f is on interval

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 $\mathbf{x_m} = \frac{x_\ell + x_r}{2}$  Use radians!  $y_\ell = f(1) = -0.1724\ 2286...$   $y_r = f(2) = +0.5514\ 8211...$  $y_{\ell}$   $y_{m}$   $y_{r}$   $|x_{r}-x_{\ell}|$ n $x_{\ell}$  $x_m$  $x_r$  $1.0000\ 0000$   $1.5000\ 0000R$   $2.0000\ 0000$ +0.152392 R + 0.5000 0000-0.028817 L + 0.2500 0000 $1.0000\ 0000$   $1.2500\ 0000L$   $1.5000\ 0000$  $1.2500\ 0000$   $1.3750\ 0000R$   $1.5000\ 0000$  $1.2500\ 0000$   $1.3125\ 0000R$   $1.3750\ 0000$  $1.2500\ 0000$   $1.2812\ 5000L$   $1.3125\ 0000$ - +0.002876 R $1.2812\ 5000$   $1.2968\ 7500R$   $1.3125\ 0000$ 0.0156 2500 MATH-305 Numerical Methods --- Bisection. Copyright © 2017-25 by Kevin G. TeBeest. Disseminating or copying without permission is prohibited

When do we stop iterating? <b>As we iterate</b> , we should see that			
a) the approach:			
b) the difference b/w approaches:			
c) the of the interval containing zero z decreases to:			
That means that each of these 3 quantities becomes			
Therefore  MATH-305 Numerical Methods Bisection. Copyright © 2017-25 by Kevin G. TeBeest. Disseminating or copying without permission is prohibited. 13			

Possible Stopping	g Tests	Solve $f(x) = 0$ for $x$
Let TOL, called a	, denote some	positive
no. of our choosing. W	Ve stop iterating and accept the last $x_{\eta}$	$_{\imath}$ as our approx.
of zero $z$ when:		
a)		
b)		
c)		IST
The latter is called the		(our favorite).
	Pemember the importance of understa	nding
Remember the importance of understanding!		
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Observations	Solve $f(x) = 0$ for $x$
Observations:	
1. At each iter'n, the of interval $[x_i]$	$_\ell,x_r$ ] is
2. Since both $\boldsymbol{x}_m$ and $\boldsymbol{z}$ are on that interval, the	ir difference
the interval's length:	
3. Consequently, the interval length is	:
In our ex, the interval length after 6 iter's is	, so
$\Big(Actual\;error\colon\;\; \mathrm{E}_{}^{}$	$\operatorname{rror}_{6}   = 0.004179 $
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<b>Error Bound</b> in using $x_m$ to approx zero $z$ :	Solve $f(x) = 0$ for $x$
	(EB.1)
So if we use the <b>interval stopping test</b> — <i>stop iterating when</i>	
	IST
then our tolerance TOL is an	:
	(EB.2)
So unlike the other stopping tests, with the IST our tolerance TC	)L
represents the we will	!
Furthermore:	
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Let L = b - a denote the length of the starting interval [a, b].

Then the error:

1. after 1 bisection is

$$|\operatorname{Error}_1| \leq$$

2. after 2 bisections is

$$|\operatorname{Error}_2| \le$$

3. after 3 bisections is

$$|\operatorname{Error}_3| \le$$

n. after *n* bisections is

$$|\operatorname{Error}_n| \leq$$

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Solve f(x) = 0 for x

So the error bound after *n* bisections is

$$|\operatorname{Error}_n| \le$$
 (EB.3)

I.e., the nth iterate  $x_m^{(n)}$  must be within \_\_\_\_\_ units of the zero z of f .

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Solve f(x) = 0 for x

Solve 
$$f(x) = 0$$
 for  $x$ 

$$|\operatorname{Error}_n| \le \frac{b-a}{2^n}$$

(EB.3)

## Example 3.

Supp. ftn f(x) satisfies the IVT on interval [-2, 6]. Determine the error bound if we bisect \_\_\_\_\_ times.

$$|\operatorname{Error}_7| \le$$

So the 7th iterate  $x_m^{(7)}$  must be within \_\_\_\_\_ units of zero  $\emph{z}$  .

If we can tolerate that much error, then we bisect 7 times and accept  $x_m^{(7)}$  .

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10

# Example 4.

$$|\operatorname{Error}_n| \le \frac{b-a}{2^n}$$

Supp. ftn f(x) satisfies the IVT on interval [-2, 6]. How many times should we bisect to ensure the error \_\_\_\_\_\_\_  $10^{-3}$  ?

ANS. We set the error bound to \_\_\_\_\_ and \_\_\_\_\_ for \_\_\_\_.

$$\frac{b-a}{2^n} \stackrel{\text{set}}{=} 10^{-3} \implies$$



Error Bound =

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		Solve $f(x) = 0$ for $x$
	$\Longrightarrow$	
	$\Longrightarrow$	
	$\implies n =$	
So bisecting	times ensures that the error will not	exceed $10^{-3}$ units.
Standing Assignment	Always rework ALL of my exs successfully yourself before attempting the HW!	
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	Solve $f(x) = 0$ for $x$
Mathematical Aside:	•
Real numbers $u$ and $v$ agree to	$\underline{}$ $d$ decimal places if
So if we choose TOL of the form TOL $= 0.5  imes 1$	$10^{-d}$ and stop iterating when
then $\boldsymbol{x}_m$ agrees with $\boldsymbol{z}$ to	decimal places.
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#### Example 5.

 $\mathsf{Solve}\ f(x)\,=\,0\ \text{ for } x$ 

Using the starting interval [-2, 6], how many times must we bisect to

guarantee \_\_\_\_\_ decimal place agreement b/w  $x_m$  and z?

$$\begin{array}{ccc} |x_r-x_\ell| \stackrel{\text{set}}{=} \\ \Longrightarrow & \frac{b-a}{2^n} & = \\ \Longrightarrow & \frac{6-(-2)}{2^n} & = \\ \Longrightarrow & 2^n & = \frac{8}{0.5\times 10^{-4}} \end{array}$$

So bisecting \_\_\_\_ times ensures that  $x_m$  agrees with z to \_\_\_\_ dec. places.

You should rework this ex!

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# **Properties of Bisection Mthd**

Solve f(x) = 0 for x

- 1. It is an \_\_\_\_\_ **mthd**. At each iter'n, we possess an interval  $[x_\ell, x_r]$  that contains zero z.
- 2. It gives \_\_\_\_-sided convergence toward zero z:
- 3. B/c of Prop 2, the \_\_\_\_\_\_ shrinks to \_\_\_\_, allowing us to use the IST: Stop iterating when

**IST** 

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		Solve $f(x) = 0$ for $x$	
4.	B/c of the IST, our tolerance TOL truly represents an error	:	
		(EB.2)	
5.	B/c of the IST, choosing TOL of the form $0.5 \times 10^{-d}$ ensur	es that	
	$x_m$ agrees with zero ${\color{red} z}$ to	dec. places.	
_			
6.	Converges than other mthds as we'	Il see.	
7. Gives a linear rate of convergence to $z$ :			
	Digits $pprox kn$ .		
_		•	
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			Solve $f(x) = 0$ for $x$
	Dec. Place Conv.	Iterations	
	1		
	2		
	3		
	4		
	5		
	6		
This mthd gives	a	rate of conv	ergence:
accuracy is approx. proportional to $n \Longrightarrow$			
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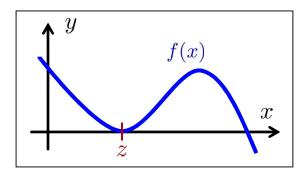
### **READ.** Try to answer these questions before reading the answers!



- 1. Explain why Bisection mthd cannot be used to approx. the zero shown, where ftn f touches the x axis tangentially at zero z without crossing through the x axis.
- 2. How would you approach this problem?

#### **Answers:**

1. If one selects a small starting interval [a, b] containing zero z, then f(a) and f(b) will **not** have opposite signs, so the conditions of the Intermediate Value Thm will not be satisfied.



2. Since f touches the x axis tangentially at x=z, then x=z is a zero of both f(x) and f'(x). Furthermore, f'(x) changes sign across x=z. So we may apply Bisection to ftn f'(x).

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#### **NOTE:**



It might be tempting to select our tolerance TOL to be  $\it very$  small, such as  $10^{-15}$ , for example. This can be problematic! Recall the number **machine epsilon** from previous notes. It is possible that we select TOL to be **so small** that the the stopping test

$$|x_r - x_\ell| \le \mathsf{TOL}$$

is **never** satisfied, in which case the code might never stop iterating, even though our iterates  $x_m^{(n)}$  become *extremely* close to zero z of f(x).

Recall that you are to **study all** pages of the notes, including those pages not covered in class. They are usually marked with ...

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# **Bisection Method Algorithm**

With  $(x_\ell,y_\ell)$  and  $(x_r,y_r)$  in hand:

- 1. Compute iterate  $x_m$ .
- 2. Compute  $y_m = f(x_m)$ .
- 3. Apply the Sign Test (IVT):

If 
$$y_\ell$$
 and  $y_m$  have opp. signs, store  $x_m$  in  $x_r$  and  $y_m$  and  $y_r$ .

Otherwise

store  $x_m$  in  $x_\ell$  and  $\,y_m$  and  $y_\ell.$ 

4. Print: iteration number,  $\boldsymbol{x}_m$ , and  $f(\boldsymbol{x}_m)$ .

Repeat Steps 1-4 until the IST is satisfied.

Recall that an algorithm is **NOT** a code.

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